

High-order potentials, high-order losses

Anton Osokin

Pushmeet Kohli

Stefanie Jegelka

Interactive image segmentation

Input:
image,
user-defined “seeds”



Output:
segmentation



MRFs for Image Labelling

$$P(Y | X) \propto \prod_i \Psi(x_i | y_i) \prod_{ij} \Psi_{ij}(y_i, y_j)$$

Posterior Probability

Likelihood Term

Pairwise
Consistency Prior



Negative log

$$E(Y) = \sum_i \varphi_i(y_i) + \sum_{ij} \varphi_{ij}(y_i, y_j)$$

Energy

Maximum a Posteriori (MAP) Inference

$$Y^* = \arg \max_Y P(Y | X)$$



Energy Minimization

$$Y^* = \arg \min_Y E(Y)$$

Image Segmentation

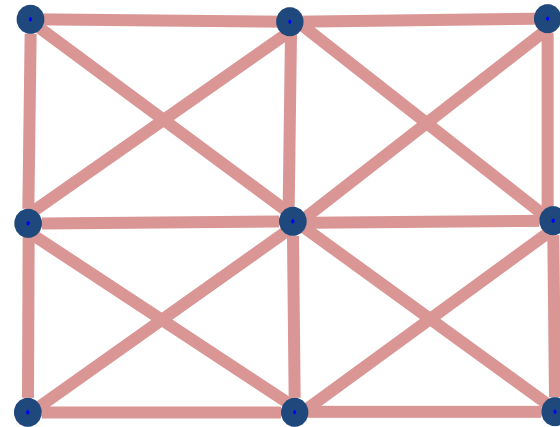
$$E(Y) = \sum_i \varphi_i(y_i) + \sum_{ij} \varphi_{ij}(y_i, y_j)$$

$$E : \{0, 1\}^N \rightarrow \mathbb{R}$$

$$0 \rightarrow \text{bg}$$

$$1 \rightarrow \text{fg}$$

N = number of pixels



Unary potentials

$$E(Y) = \sum_i \varphi_i(y_i) + \sum_{ij} \varphi_{ij}(y_i, y_j)$$

$$\sum_i c_i(1 - y_i)$$

Pixel color



Unary Cost c_i

Dark (negative) Bright (positive)

Pairwise potentials

$$E(Y) = \sum_i \varphi_i(y_i) + \sum_{ij} \varphi_{ij}(y_i, y_j)$$



$$\sum_{ij} d_{ij} |y_i - y_j|$$

Smoothness Prior

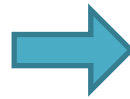
Discontinuity

Cost d_{ij}

Energy minimization

$$E(Y) = \sum_i c_i(1 - y_i) + \sum_{ij} d_{ij}|y_i - y_j|$$

If all $d_{ij} \geq 0$ then the energy is submodular and can be minimized with max-flow/min-cut algorithm.



Problems

- Encourages Short Boundaries

[Jegelka & Bilmes, 11]



Image



Segmentation

- Does not enforce connectivity

[Vincente et al.] [Nowozin and Lampert] [Rhemann et al.]

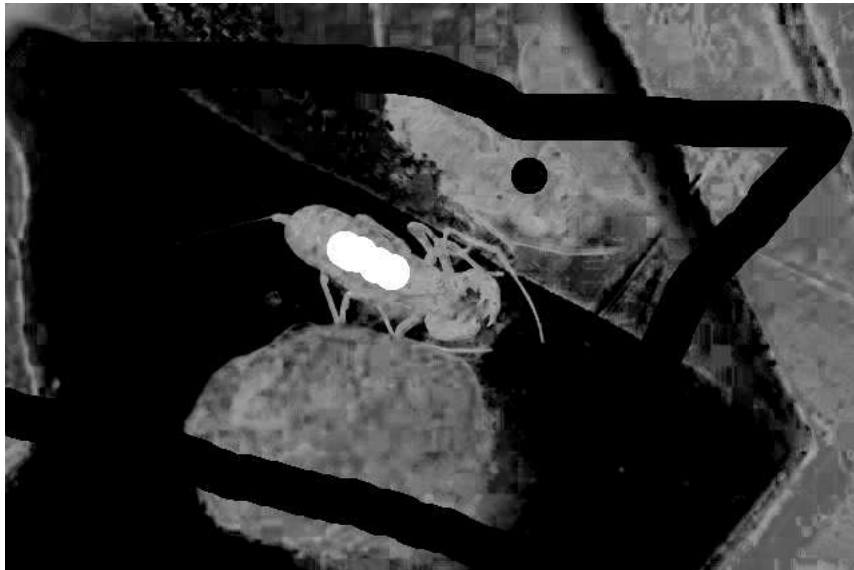
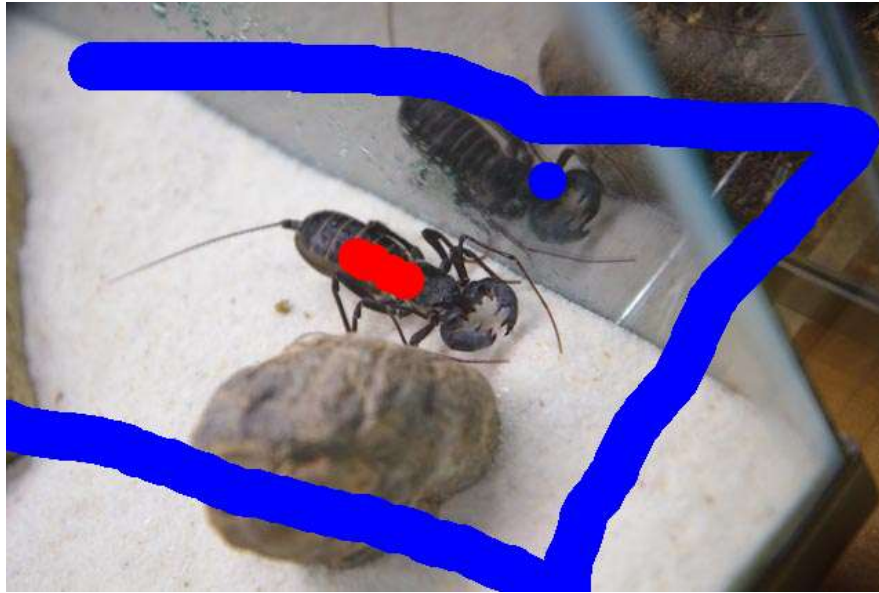
- Inconsistent labeling of similar pixels

[Kohli et al. 07, 08]

- Consistency with Area/Boundary length

[Boykov et al, 07][Lim et al, 08]

Example



Example: GraphCut results

Ground truth:



Pairwise
weight = 1.5



Pairwise
weight = 1.0



Pairwise
weight = 0.6



Pairwise
weight = 0.5



Part 1: Cooperative cut model

Overcoming short-boundary bias

$$E(Y) = \sum \varphi_i(y_i) + \sum d_{ij} |y_i - y_j|$$

↓
Encourages short
boundaries



Image



Segmentation

**Penalize types of
boundaries not the actual
number of boundaries!**

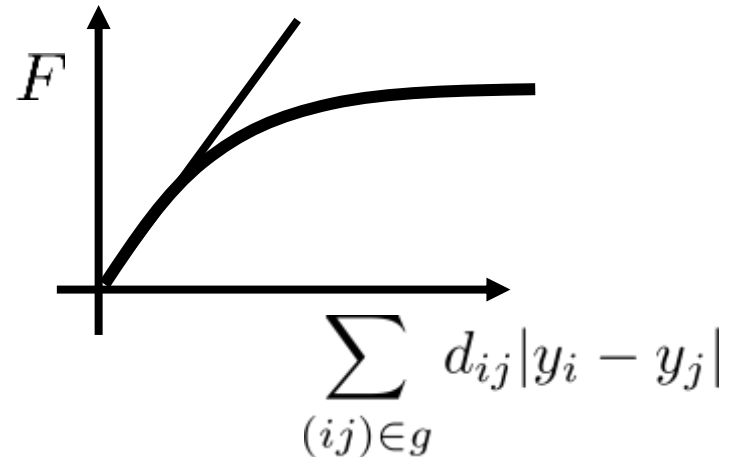
**Cooperative cut model
[Jegelka and Bilmes, 11]**

Overcoming short-boundary bias

$$E(Y) = \sum \varphi_i(y_i) + \cancel{\sum d_{ij}|y_i - y_j|} + \sum h_g(Y)$$

$$h_g(Y) = F\left(\sum_{(ij) \in g} d_{ij}|y_i - y_j|\right)$$

- Divide edges into different types
- Incorporate a higher order consistency potential over the edges



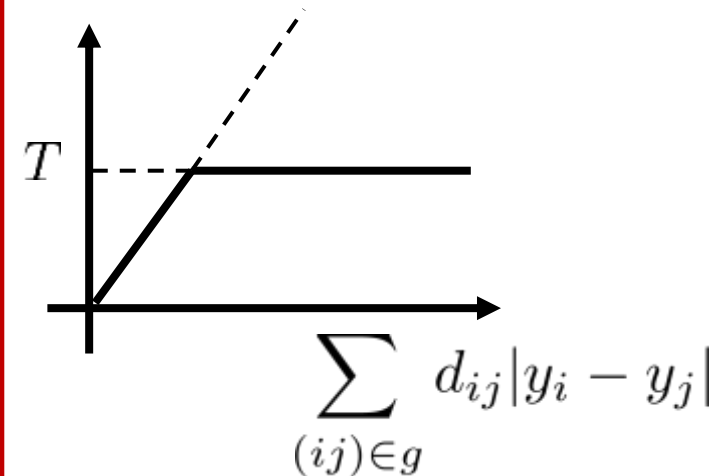
Constructing groups

For each edge construct a feature vector:
absolute difference between two nodes.

Exclude edges with no difference.

Cluster all remaining edges into 10 clusters using K-means.

For each cluster use a truncated linear
Function F



Example

Ground truth:



Pairwise
weight = 1.0



Cooperation



Example

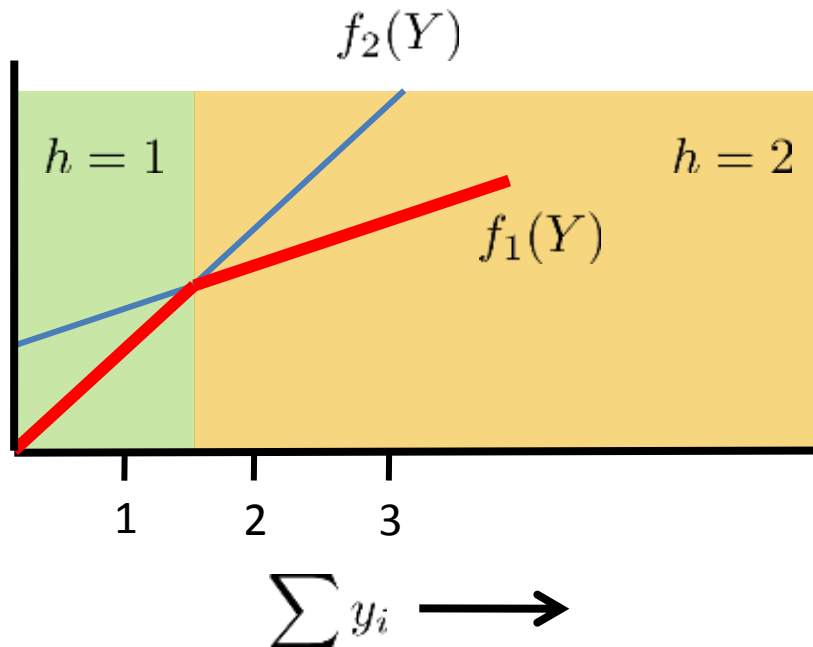
Ground truth:



Cooperation



Transformation to pairwise energy



$$f(y) = \min(f_1(Y), f_2(Y))$$

Lower envelop of
concave
functions is
concave

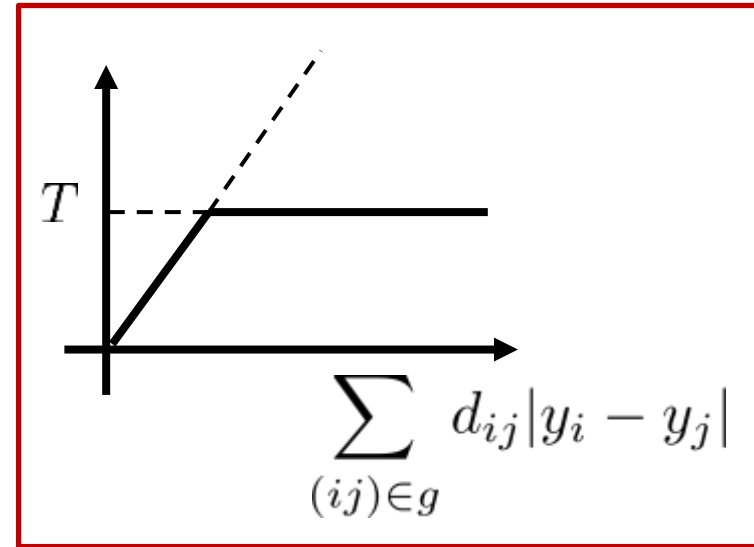
$$\min_Y f(Y) = \min_{Y, h \in \{0,1\}} h f_1(Y) + (1 - h) f_2(Y)$$

Higher Order
Submodular Function

Quadratic Submodular
Function

Our transformation

$$H_g(Y) = \min \left\{ \sum_{(ij) \in g} d_{ij} |y_i - y_j|, \quad T \right\}$$



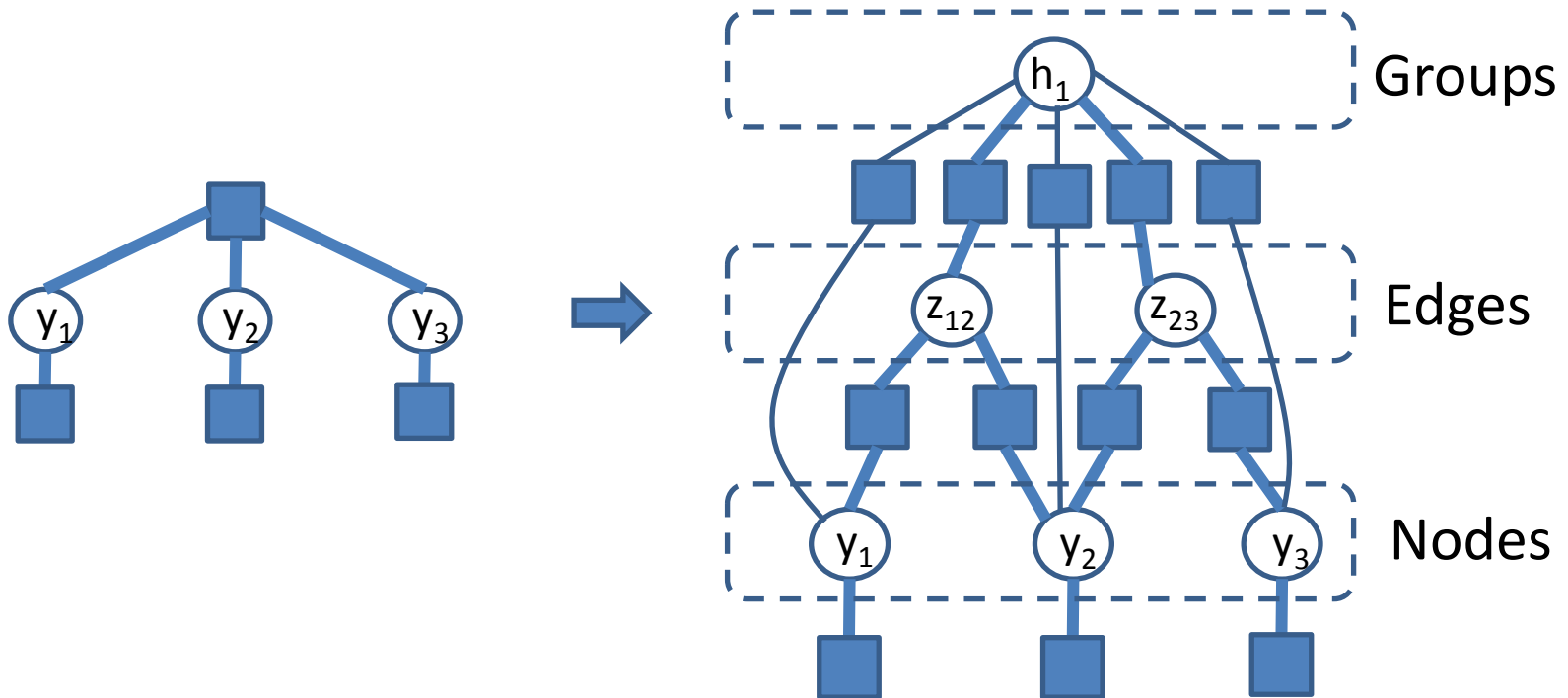
+ Switching variables h_g

$$H_g(Y) = \min_{h_g \in \{0,1\}} h_g \sum d_{ij} (y_i + y_j - 2y_i y_j) + T(1 - h_g)$$

+ Standard reduction for $-h_g y_i y_j$ using variable z_{ij}

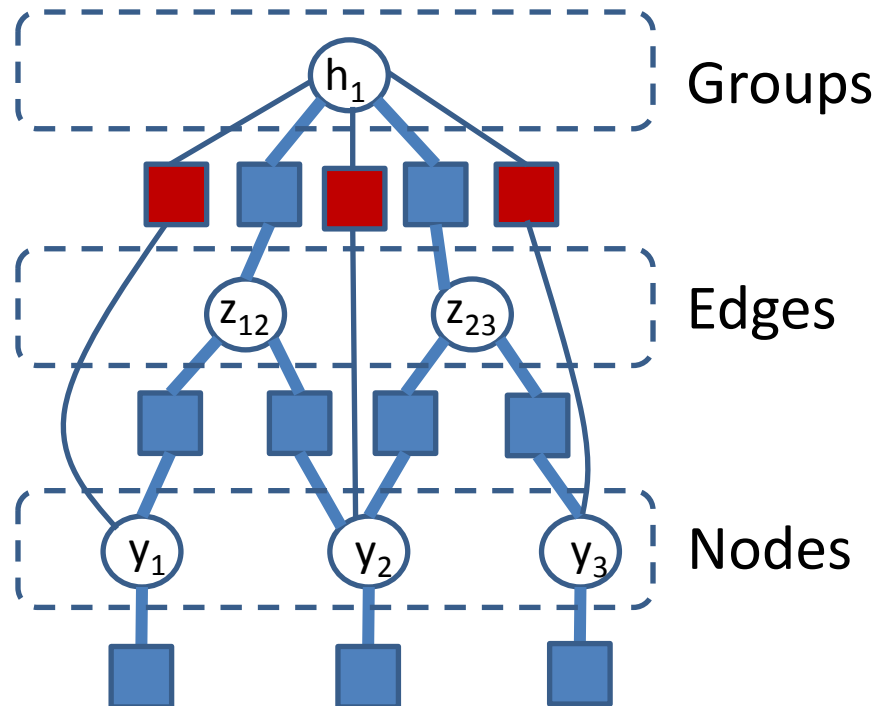
$$-h_g y_i y_j = \min_{z_{ij} \in \{0,1\}} (-z_{ij} (y_i + y_j + h_g - 2))$$

Transformation



Observations

- 1) non-submodular factors are concentrated around h_g
- 2) if we fix h_g the energy becomes submodular



Algorithms

- 1) Exhaustive search over h_g
 - a) dynamic graph cuts [Kohli and Torr, 05]
 - b) special order of search

- 2) Different greedy strategies
 - a) descent till convergence
 - b) 1 pass over variables

- 3) Iterative bound minimization [Jegelka and Bilmes, 11]

Qualitative results



Graph cut



Global minimum

[Jegelka&Bilmes, 11]

Quantitative results

Method	Energy	Time	Error
GraphCut	1.0	0.19	1.61
It. bound min.	0.39	0.47	0.77
Global minimum	0.0	14.32	0.73
Greedy	0.0	2.37	0.73
1 pass	0.03	1.23	0.87

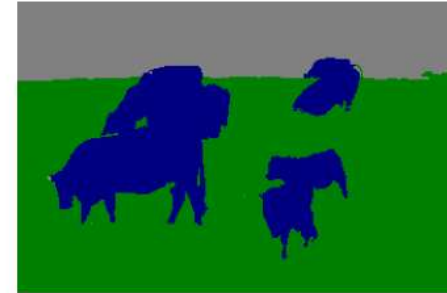
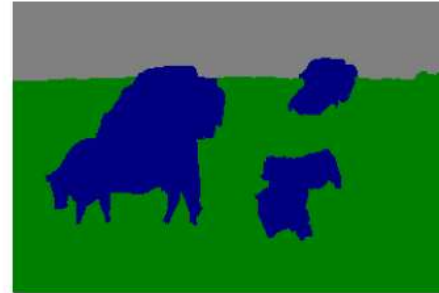
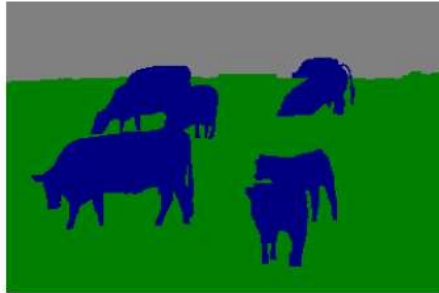
Multilabel results

Image

Ground Truth

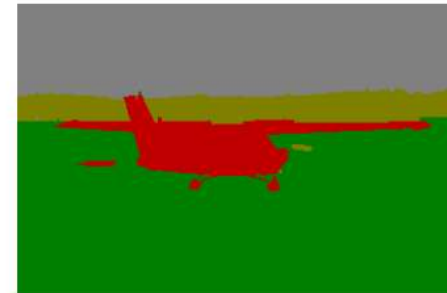
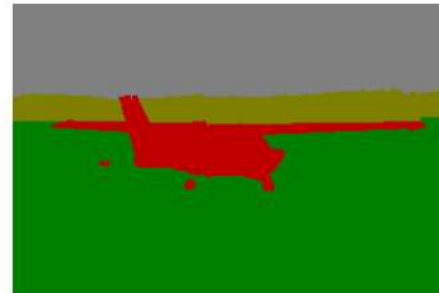
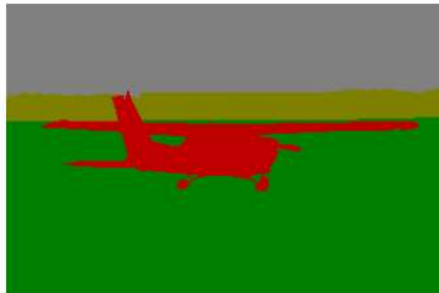
Pairwise RF results
 $\epsilon = 3.00\%$

Our result
 $\epsilon = 2.63\%$



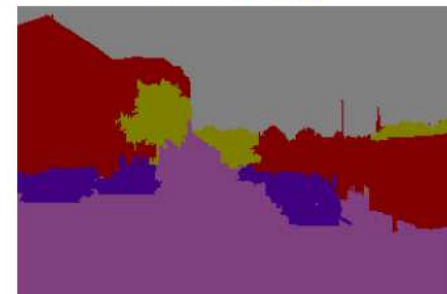
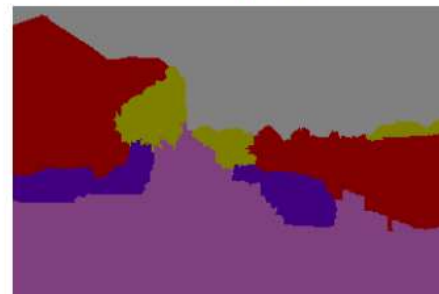
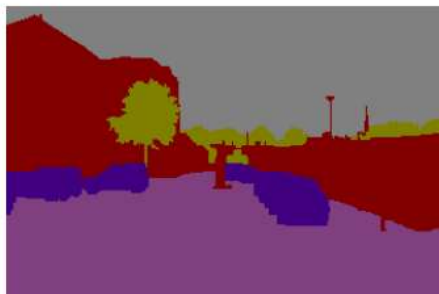
$\epsilon = 2.39\%$

$\epsilon = 2.14\%$



$\epsilon = 5.12\%$

$\epsilon = 4.53\%$



Part 2: High-order losses

Training setup

Data: $\{X^i, Y^i\}, i = 1, \dots, N$



X



Y

Energy parameterization: $E(X, Y, w) = -w^T \psi(X, Y)$

Goal: find parameters such that model produces “good” results

“Good” is defined by loss function $\Delta(Y, Y^i)$

Large-margin approach

$$\begin{aligned} \min_{w, \xi \geq 0} \quad & \frac{1}{2} \|w\|^2 + \frac{C}{N} \sum_{i=1}^N \xi_i, \\ \text{s.t.} \quad & w^\top (\psi(X^i, Y) - \psi(X^i, Y^i)) + \Delta(Y, Y^i) \leq \xi_i, \quad \forall Y \end{aligned}$$

The problem can be solved with cutting-plane method.

Key step: finding the most violated constraint

$$\arg \min (-w^\top \psi(X^i, Y) - \Delta(Y, Y^i))$$

Loss-related problems

- Correspondence to human perception
- We are not optimizing the loss, but its hinge-bound
- Biased loss estimates
 - Certain losses have higher Generalization error

Simple (decomposable) losses

Hamming distance: $\Delta(Y, Y^k) = \sum_i [y_i \neq y_i^k]$

Weighted Hamming distance:

$$\Delta(Y, Y^k) = \sum_i c_i(Y_k) [y_i \neq y_i^k]$$

Hamming distance averaged over classes (HAC):

$$\Delta(Y, Y^k) = \frac{1}{2} \sum_{n \in \{0,1\}} \frac{\sum_i [y_i \neq n] [y_i^k = n]}{\sum_i [y_i^k = n]}.$$

High-order losses

[Tarlow and Zemel, 2012]

PASCAL VOC loss (Jaccard distance):

$$\frac{\#(\text{true positives})}{\#(\text{true positives}) + \#(\text{false positives}) + \#(\text{false negatives})}$$

Loss augmented inference by message-passing

High-order losses

[Pletscher and Kohli, 2012]

Observation:

the loss enters the energy minimization with the negative sign,
so supermodular losses are good

Example: “count” loss

$$\Delta(Y, Y^k) = \left| \sum_i y_i - \sum_i y_i^k \right|$$

More generally, any upper envelope of linear functions can be done

[Kohli and Kumar, 2010]

Family of losses

S – arbitrary sets of pixels

$$\Delta(Y, Y^k) = \sum_{S \in \mathcal{S}} c_S \left| \sum_{i \in S} y_i - \sum_{i \in S} y_i^k \right|$$

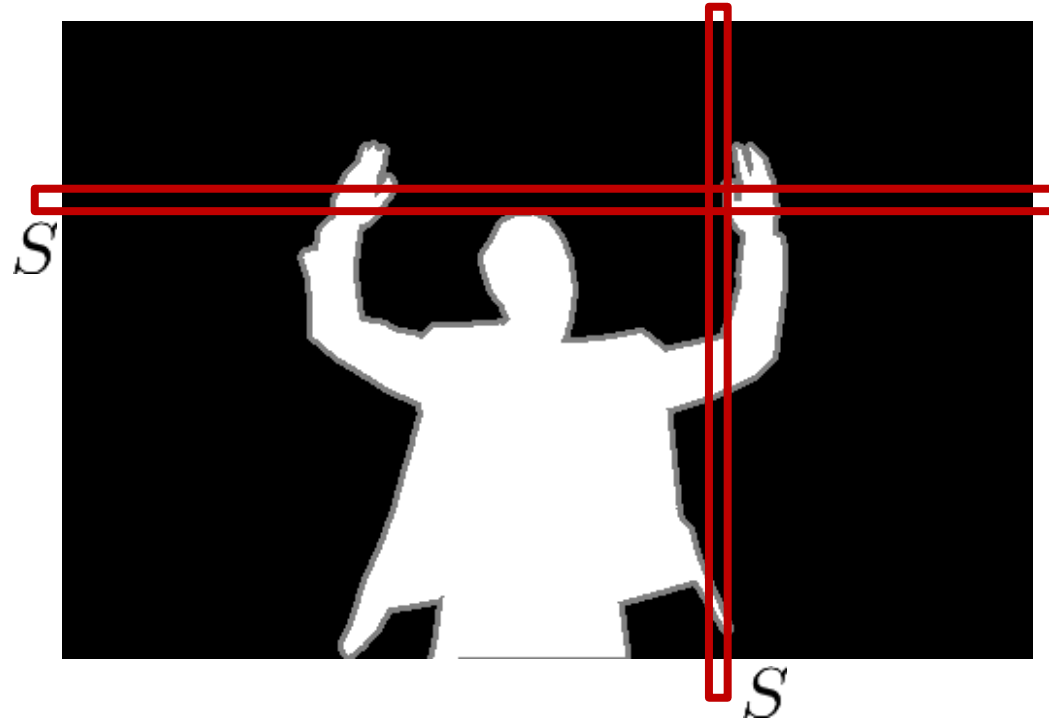
Special cases:

- Hamming (weighted, averaged) loss
- “Count” loss

Silhouette loss

S – rows and columns

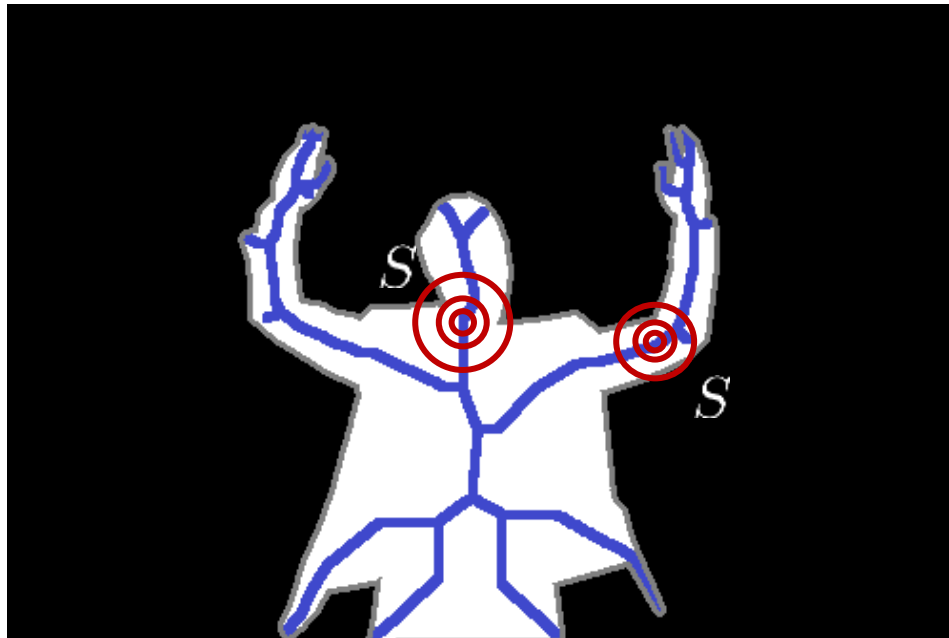
$$\Delta(Y, Y^k) = \sum_{S \in \mathcal{S}} c_S \left| \sum_{i \in S} y_i - \sum_{i \in S} y_i^k \right|$$



Skeleton based loss

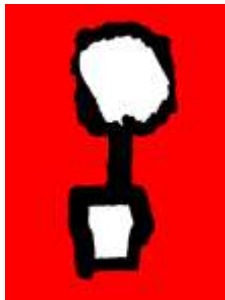
S can depend on the groundtruth

$$\Delta(Y, Y^k) = \sum_{S \in \mathcal{S}} c_S \left| \sum_{i \in S} y_i - \sum_{i \in S} y_i^k \right|$$

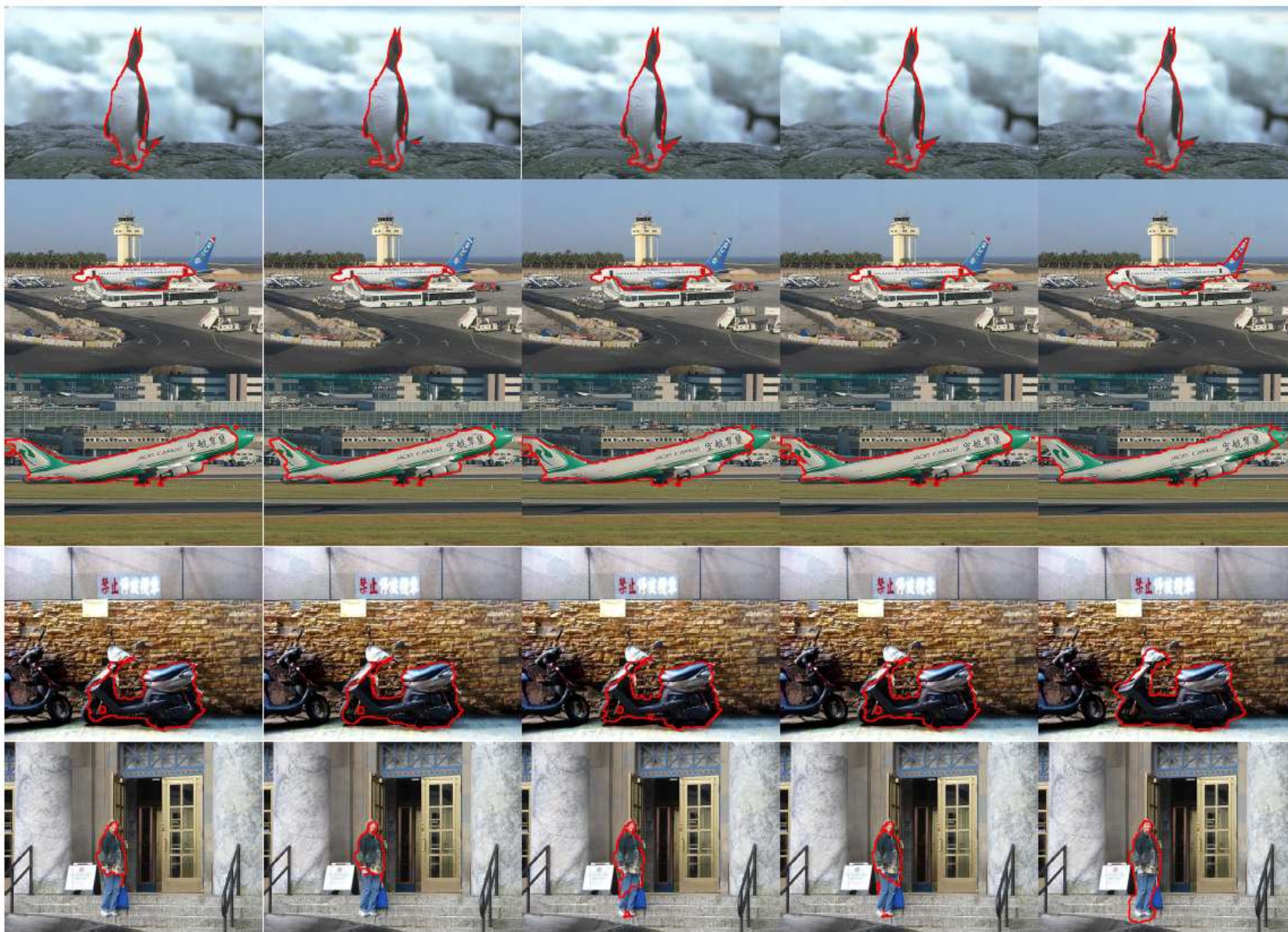


Experimental setup

- 60 images that are “more difficult”
[Gulshan et al., 2010; Pletscher and Kohli, 2012]
- 8-neighborhood
- 51 unary features:
 - color (GMM)
 - geodesic distances from seeds
- 6 pairwise features: (contrast sensitive) Potts
- Large enough seeds to make the problem easier



Results



Hamming loss

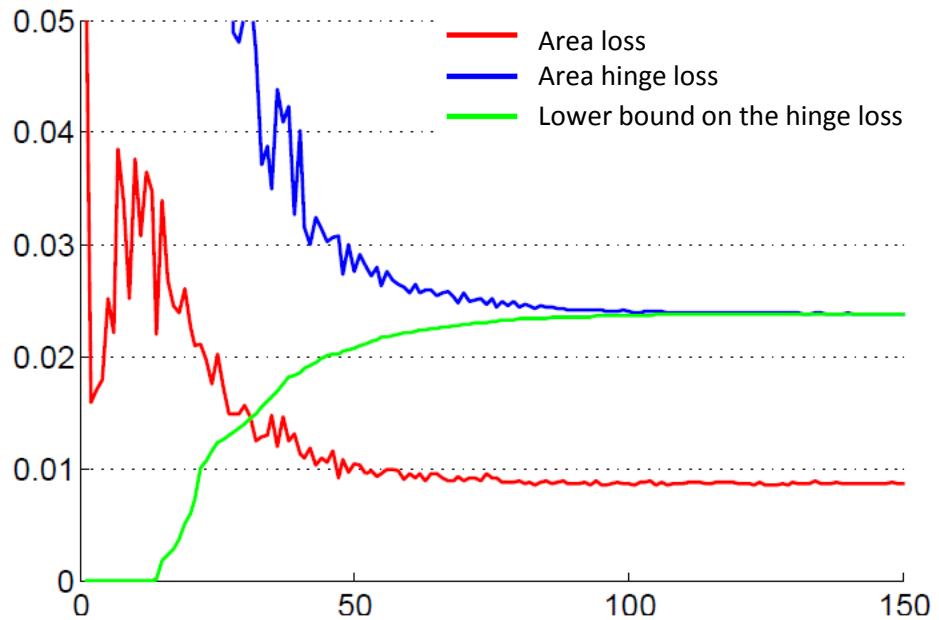
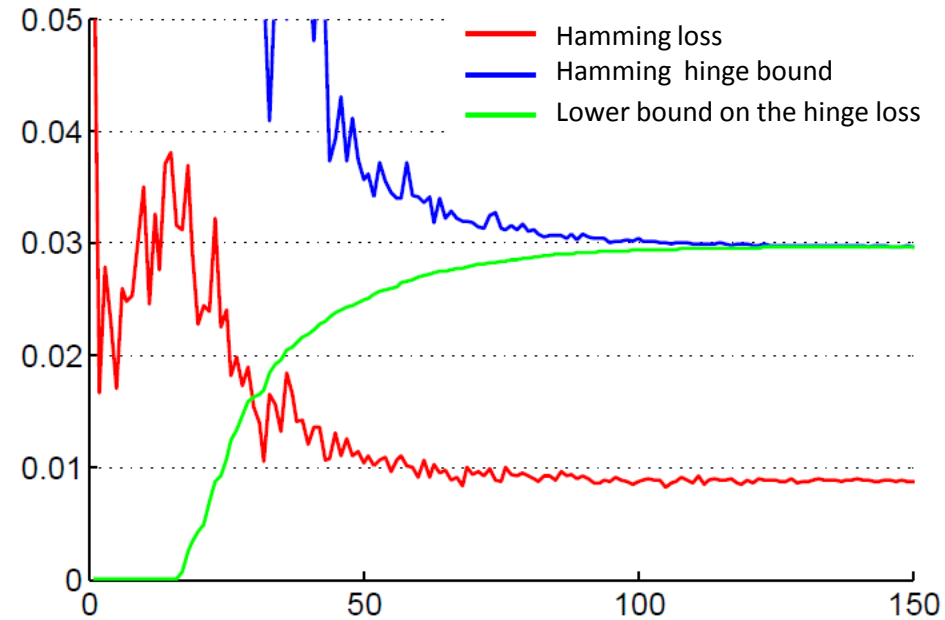
Weighted
Hamming loss

HAC

Silhouette

Skeleton

Hinge bound is not tight!



Correlation between a loss and a hinge bound on the training set

Loss	H hinge	wH hinge	HAC hinge	area hinge
H	0.11	0.28	0.28	0.54
wH	0.04	0.27	0.31	0.63
HAC	-0.34	0.23	0.42	0.51
Area	0.20	0.16	0.23	0.74
J	-0.25	0.27	0.44	0.49

Training with one loss, testing with the other

Training Loss	Hamming		weighted Hamming		HAC		area	
	Train	Test	Train	Test	Train	Test	Train	Test
Hamming	1.1953	1.3319	12.222	12.613	4.4621	4.8987	0.5841	0.6743
HammingW	1.2014	1.4316	12.278	12.886	4.7536	5.2949	0.6924	0.8452
HAC	1.3431	1.4834	11.987	12.303	2.1226	2.3265	0.8563	0.8916
Area	1.1324	1.3091	11.901	12.408	3.7944	4.3215	0.3466	0.6807

Thank you!