i. Crete, Greece, 4 October 2014 - 11 October 2014

Probabilistic analysis of an approximation algorithm for the m-peripatetic salesman problem on random instances unbounded from above.

Edward Gimadi, Alexey Istomin, Ivan Rykov, Oxana Tsidulko

Sobolev Institute of Mathematics SB RAS Novosibirsk State University An algorithm \overline{A} has performance bounds $\overline{\varepsilon_A(n)}, \delta_A(n)$ if

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An algorithm A is called asymptotically optimal (exact)

on a class of instances, if there exist performance bounds s.t.

$$\varepsilon_A(n) \xrightarrow[n \to \infty]{} 0, \ \delta_A(n) \xrightarrow[n \to \infty]{} 0.$$

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But most of this problems are NP-hard, like the well-known Travelling Salesman Problem.

The problem is to find

m edge-disjoint Hamiltonian cycles H_1, \ldots, H_m in a given complete graph G = (V, E)with given weight functions $w_i : E \to \mathbf{R}_+, i = 1, \ldots, m$,

such that

$$W_1(H_1) + \ldots + W_m(H_m) = \sum_{i=1}^m \sum_{e \in H_i} w_i(e) \rightarrow \min(\max).$$

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Applications of the *m*-PSP include

Design of patrol tours

in order to avoid constantly repeating the same tour and thus enhance the security.

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Optimization of delivery routes.

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- deterministic and random instances,
- arbitrary, Euclidean and metric weight functions of edges,
- common and different weight functions of *m* Hamiltonian cycles
- special classes of graphs where the weights of the edges belong to a given finite and infinite set of numbers.

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Some previous results for *m*-PSP

• NP-hardness [De Kort 1991].

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- Polyhedral space with a bounded number of facets (Shenmaier 2010)

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- We have obtained the performance guarantees of this algorithm for certain classes of random inputs of the problem.
- We have justified the conditions for the algorithm to be asymptotically exact on the considered classes of inputs.

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Input:

A complete *n*-vertex graph G = (V, E) with weight functions $w_i : E \to \mathbf{R}_+, i = 1, ..., m$, where m < n/4

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Main idea:

modification of the greedy algorithm; finding each Hamiltonian cycle by turns.

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The description of Algorithm \widetilde{A} for minimum-weight *m*-PSP

Stage $i = 1, \ldots, m$.

In Stage *i* we consider given graph G with weight function w_i and construct Hamiltonian cycle H_i in 3 steps.
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This partial path is converted to a Hamiltonian cycle H_i via procedure \mathbb{P} .

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For the formation of all further Hamiltonian cycles i + 1, ..., m forbid all edges in H_i and the corresponding reverse edges.

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- given undirected \hat{n} -vertex graph $H(V_H, E_H)$ such that $\forall v \in V_H \ deg(v) > \hat{n}/2$,
- **2** given vertices $u, v \in V_H$.

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- Time complexity: $O(\hat{n}^2)$

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Description of the procedure $\mathbb P$

While $1 \le k \le \hat{n}$ • Let $P = \{u_1, \dots, u_k\}$ be the constructed path.



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Description of the procedure $\mathbb P$

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If there is an edge {u_k, w} ∈ H, where w ∉ P, and w = v ↔ k = n̂ - 1, then
P := {u = u₁,..., u_k, u_{k+1} = w}

Otherwise:

• Randomly choose a vertex $w \notin P$ ($w = v \leftrightarrow k = \hat{n} - 1$).



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- $P := \{u = u_1, \ldots, u_i, u_k, \ldots, u_{i+1}, w\}$



• Suppose, there is no edge $\{u_i, u_{i+1}\} \in P$ such that $\{u_k, u_i\}$ and $\{w, u_{i+1}\} \in E_H$.

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Contradiction.

We represent an input for the m-PSP as a

 $m \times n \times n$ cost matrix $C = (c_{ijk})$, where c_{ijk} is equal to the *i*-th weight function $w_i(e)$ of edge e = (j, k), $i = \overline{1, m}, j, k = \overline{1, n}$.

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Random input for the m-PSP is a

 $m \times n \times n$ cost matrix $C = (c_{ijk})$, which elements c_{ijk} are independent identically distributed random real numbers.

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Definition of distribution functions of majorizing type

The distribution function $\mathcal{F}'(x)$ is a function of \mathcal{F} -majorizing type if

 $\mathcal{F}'(x) \geq \mathcal{F}(x)$ for every x

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• of \mathcal{F}_{β} -majorizing type, where $\mathcal{F}_{\beta}(x)$ is exponential distribution with parameter $\beta = \beta_n$: $\mathcal{F}_{\beta}(x) = 1 - \exp\left(\frac{x - a_n}{\beta}\right), \ x \ge a_n > 0.$ An algorithm \overline{A} has performance bounds $\overline{\varepsilon_A(n)}, \delta_A(n)$ if

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Probabilistic analysis of Algorithm \widetilde{A}

Let $H_i = \{e_1^{(i)}, \dots, e_n^{(i)}\}$ is *i*-th constructed Hamiltonian cycle

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Denote $\xi_{is} = w_i(e_s^{(i)})$. Then

$$Pr\Big\{\sum_{i=1}^{m}\sum_{s=1}^{n}\xi_{is}>(1+arepsilon_{\widetilde{\mathcal{A}}})OPT\Big\}\leq\delta_{\widetilde{\mathcal{A}}}.$$

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Probabilistic analysis of Algorithm \widetilde{A}

Main ideas of the probabilistic analysis

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- Weight ξ_{is} of an edge chosen in Step 1(greedy algorithm) is estimated from above as minimum of n 2i s + 2 elements of random input.

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- All ξ_{is} are independent random variables.
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- Use the inequality $OPT \ge a_n mn$
- Use Petrov's Theorem

Petrov V.V. 'Limit theorems for sums of independent random variables', 1987

Petrov's Theorem

Consider independent random variables η_1, \ldots, η_n and $S = \sum_{k=1}^n \eta_k$. Let there be positive constants g_1, \ldots, g_n and T, such that

$$\mathbf{E}e^{t\eta_k} \le e^{\frac{g_k t^2}{2}}, \ 0 \le t \le T, \ k = 1, \dots, n$$

Denote $\mathcal{G} = \sum_{k=1}^{n} g_k$. Then

$$\mathsf{Pr}\{S \ge x\} \le \begin{cases} e^{\frac{-x^2}{2G}}, & 0 \le x \le \mathcal{GT}, \\ e^{\frac{-Tx}{2}}, & x \ge \mathcal{GT} \end{cases}$$

Where $\mathbf{E}X$ is the expected value of random variable X.

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To apply Petrov's theorem we used the previous results from the following papers to obtain constants g_{is} for the random variables ξ_{is}

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For uniform distribution function:

E. Kh. Gimadi,Yu. V. Glazkov *An asymptotically exact algorithm for one modification of planar three-index assignment problem//* Journal of Applied and Industrial Mathematics December 2007, Volume 1, Issue 4, pp 442-452

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To apply Petrov's theorem we used the previous results from the following papers to obtain constants g_{is} for the random variables ξ_{is}

For uniform distribution function:

E. Kh. Gimadi,Yu. V. Glazkov *An asymptotically exact algorithm for one modification of planar three-index assignment problem//* Journal of Applied and Industrial Mathematics December 2007, Volume 1, Issue 4, pp 442-452

For exponential distribution function:

E. Kh. Gimadi, A. Le Gallou, A. V. Shakhshneyder, *Probabilistic analysis* of an approximation algorithm for the traveling salesman problem on unbounded above instances// Journal of Applied and Industrial Mathematics April 2009, Volume 3, Issue 2, pp 207-221.

The performance bounds of the algorithm obtained for random inputs of m-PSP with some distribution function F(x) will also be true for random inputs with any distribution function of F(x)-majorizing type.

Statement 1

Let $\xi_1, ..., \xi_k$ be the independent random variables with distribution function F(x), Let $\hat{F}(x)$ be the distribution function of $\xi = \min(\xi_1, ..., \xi_k)$, Let $\eta_1, ..., \eta_k$ be the independent random variables with distribution function G(x), Let $\hat{G}(x)$ be the distribution function of $\eta = \min(\eta_1, ..., \eta_k)$.

Then for any x

$$F(x) \leq G(x) \Rightarrow \hat{F}(x) \leq \hat{G}(x).$$

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Then for any x

$$F(x) \leq G(x) \Rightarrow \hat{F}(x) \leq \hat{G}(x).$$

The statement follows directly from the equations

$$\hat{F}(x) = 1 - (1 - F(x))^k$$
 and $\hat{G}(x) = 1 - (1 - G(x))^k$.

Statement 2

Let $P_{\xi}, P_{\eta}, P_{\zeta}, P_{\chi}$ be the distribution functions of random variables ξ, η, ζ, χ , respectively. And let ξ and ζ be independent, η and χ be independent. Then

$$(\forall x \ P_{\xi}(x) \leq P_{\eta}(x)) \land (\forall y \ P_{\zeta}(y) \leq P_{\chi}(y)) \Rightarrow (\forall z \ P_{\xi+\zeta}(z) \leq P_{\eta+\chi}(z)).$$

Proof

$$P_{\xi+\zeta}(x) = \int_{-\infty}^{\infty} P_{\xi}(x-y) dP_{\zeta}(y) \le \int_{-\infty}^{\infty} P_{\eta}(x-y) dP_{\zeta}(y)$$
$$= P_{\eta+\zeta}(x) = \int_{-\infty}^{\infty} P_{\zeta}(x-y) dP_{\eta}(y) \le \int_{-\infty}^{\infty} P_{\chi}(x-y) dP_{\eta}(y) = P_{\eta+\chi}(x).$$

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Theorem

Let the distribution function F(x) of random inputs of m-PSP be s.t.

 $F(x) \geq P(x).$

Then Algorithm \tilde{A} has the same performance guarantees $(\varepsilon_{\tilde{A}}, \delta_{\tilde{A}})$ on these random inputs, as it would have on random inputs with distribution function P(x).

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Corollary (for example)

The performance guarantees of Algorithm \widetilde{A} obtained in the case of random inputs with **exponential** distribution with a parameter β will also hold in case of random inputs with **truncated normal** distribution function with a certain parameter σ_n .

For the random inputs of m-PSP with the distribution function of **UNI**[a_n , b_n]-**majorizing type**, $0 < a_n < b_n$, Algorithm \widetilde{A} is asymptotically exact with the following performance guarantees

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for $2 \le m \le \ln n$

$$\varepsilon_{\widetilde{A}} = O\left(\frac{b_n/a_n}{n/\ln n}\right), \ \ \delta_{\widetilde{A}} = n^{-9},$$

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for $\ln n < m \le n^{1-\theta} < n/4$

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The paper

Э.Х. Гимади, А.М. Истомин, И.А. Рыков, О.Ю. Цидулко. Вероятностный анализ приближённого алгоритма для решения задачи нескольких коммивояжеров на случайных входных данных, неограниченных сверху // Труды ИММ УрО РАН. 2014. Т. 20, № 2, С. 88-98.

Probabilistic analysis of an approximation algorithm for the m-peripatetic salesman problem on random instances unbounded from above.

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Thank you for your attention!

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- Input: A complete *n*-vertex graph G = (V, E) with weight functions $w_i : E \to \mathbf{R}_+, i = 1, ..., m$, where m < n/4
- Output: *m* edge disjoint Hamiltonian cycles *H*₁,..., *H_m*
- Time complexity: $O(mn^2)$

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- Output: *m* edge disjoint Hamiltonian cycles *H*₁,..., *H_m*
- Time complexity: $O(mn^2)$
- Main idea: modification of the greedy algorithm; finding each Hamiltonian cycle by turns.

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- *i* number of current Hamiltonian cycle.
- F set of forbidden edges (at first $F = \emptyset$).
 - Consider the traveling salesman problem for graph $G \setminus F$ with weight function w_i .



Randomly choose the first vertex to start with. Let it be vertex 1.
 Among all neighbors of 1 randomly choose a vertex v.
 Edward Gimadi, Alexy Istomin, Ivan Rykov, Oxana Tsiduko

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- *i* number of current Hamiltonian cycle.
- s number of processed vertices.
 - While s < n 4i



i = 1, s = 1.

go to the nearest unvisited vertex, except vertex v.
s := s + 1.

- *i* number of current Hamiltonian cycle.
- s number of processed vertices.
 - While s < n 4i



i = 1, s = 2.

go to the nearest unvisited vertex, except vertex v.
s := s + 1.

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- *i* number of current Hamiltonian cycle.
- s number of processed vertices.
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i = 1, s = 3.

go to the nearest unvisited vertex, except vertex v.
s := s + 1.

- *i* number of current Hamiltonian cycle.
- s number of processed vertices.
 - While s < n 4i



i = 1, s = 4.

go to the nearest unvisited vertex, except vertex v.
s := s + 1.

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- s number of processed vertices.
 - While s < n 4i



i = 1, s = 5.

go to the nearest unvisited vertex, except vertex v.
s := s + 1.
• Consider a subgraph *H* induced by all unprocessed vertices, and the last processed vertex:



- Using procedure \mathbb{P} build a path with endpoints u_{n-4i} , v,
- Complete the Hamiltonian cycle H_i.
- For further stages forbid all edges ∈ H_i and the corresponding reverse edges.

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In Step 1.



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• the degree of each vertex at the beginning of Step 1: deg(v) = n - 2 - 2(i - 1) = n - 2i

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Relevance of Algorithm A

In Step 1.



- the degree of each vertex at the beginning of Step 1: deg(v) = n - 2 - 2(i - 1) = n - 2i
- the greedy algorithm makes n 4i steps, so it is always possible to make the next step.

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Consider subgraph H constructed in Step 2.



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Consider subgraph H constructed in Step 2.



• Since
$$s = n - 4i$$
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• Since
$$s = n - 4i$$
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• $\forall v \in V_H \deg(v) \ge (4i + 1 - 1) - 2(i - 1) = 2i + 2$

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Consider subgraph H constructed in Step 2.



- Since s = n 4i, $|V_H| = n s + 1 = 4i + 1$.
- $\forall v \in V_H \deg(v) \ge (4i+1-1)-2(i-1)=2i+2$
- Thus we can use procedure \mathbb{P} for this graph.

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• Step 1 (greedy algorithm) – $O(n^2)$

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- Step 1 (greedy algorithm) $O(n^2)$
- Step 2 (procedure P_H) $O(n^2)$

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- Step 2 (procedure P_H) $O(n^2)$

Total time complexity: $O(mn^2)$.

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