# xgBoost

#### Victor Kitov

### Introduction

- xgBoost one of many open source realizations of gradient boosting.
- Very successful:
  - among 29 kaggle competitions on Kaggle in 2015 17 winning solutions used xgBoost and among these 8 used only xgBoost.
- Success reasons:
  - optimization criteria is flexible enough to fit any loss function
  - optimization criteria has regularization.
  - optimized for big data
  - optimized for sparse data
- We will consider only optimization criteria here.

## Boosting reminder

• Boosting prediction is performed with sum of *M* predictor functions:

$$\widehat{y}_i = \sum_{m=1}^M f_m(x_i),$$

where each  $f_m$  is a regression tree:

- $f_m \in \{f(x) = w_{q(x)}\},\$
- $q: \mathbb{R}^D \to T, w \in \mathbb{R}^T$
- T is the number of trees.
- Each tree  $f_m$ :
  - has independent tree structure q(x) and weights w
  - is built greedily after optimizing  $f_1, f_2, ... f_{m-1}$  to achieve greatest score improvement.

## Optimization score

At step *m* we optimize:

$$L^{(m)}(f_m) = \sum_{n=1}^{N} \mathcal{L}(y_n, \hat{y}_n^{(m-1)} + f_m(x_n)) + R(f_m)$$
(1)

Here:

- $\mathcal{L}(y_n, \widehat{y}_n^{(m)})$  is the loss induced by predicting  $y_n$  with  $\widehat{y}_n$
- $R(f_m) = \gamma T + \frac{1}{2}\lambda ||w||^2$  is the regularization term, penalizing  $f_m$  for complexity.

  - $\gamma T$  penalizes the number of leaves  $\|w\|^2 = \sum_{t}^{T} w_t^2$  penalizes the magnitude of leaf predictions.

### Taylor expansion

• Using Taylor expansion expand  $\mathcal{L}(y_n, \widehat{y}_n^{(m)})$  into

$$\mathcal{L}(y_n, \widehat{y}_n^{(m)}) \approx \mathcal{L}(y_n, \widehat{y}_n^{(m-1)}) + g_n f_m(x_n) + \frac{1}{2} h_n f_m^2(x_n)$$
(2)

where

$$g_n = \frac{\partial}{\partial \widehat{y}^{(m-1)}} \mathcal{L}\left(y_n, \widehat{y}_n^{(m-1)}\right), \qquad h_n = \frac{\partial^2}{\partial^2 \widehat{y}^{(m-1)}} \mathcal{L}\left(y_n, \widehat{y}_n^{(m-1)}\right)$$

• Plugging (2) into (1), obtain:

$$L^{(m)}(f_m) \approx \sum_{n=1}^{N} \left[ \mathcal{L}(y_n, \hat{y}_n^{(m-1)}) + g_n f_m(x_n) + \frac{1}{2} h_n f_m^2(x_n) \right] + R(f_m)$$
(3)

#### Taylor expansion

• Removing constant terms from (3), we obtain the following approximation to initial loss:

$$\widehat{\mathcal{L}}^{(m)}(f_m) = \sum_{n=1}^{N} \left[ \mathcal{L}(y_n, \widehat{y}_n^{(m-1)}) + g_n f_m(x_n) + \frac{1}{2} h_n f_m^2(x_n) \right] (4) + \gamma T + \frac{1}{2} \lambda \sum_{t=1}^{T} w_t^2$$
(5)

• Define  $I_t = \{n : q(x_n) = t\}$ . Then (4) can be rewritten as:

$$\widehat{L}^{(m)}(f_m) = \sum_{t=1}^{T} \left[ \left( \sum_{n \in I_t} g_n \right) w_t + \frac{1}{2} \left( \sum_{n \in I_t} h_n + \lambda \right) w_t^2 \right] + \gamma T$$
(6)

### Optimized loss

• Optimizing (6) with respect to  $w_t$ , we obtain:

$$w_t^* = -\frac{\sum_{n \in I_t} g_n}{\sum_{n \in I_t} h_n + \lambda}$$

• Plugging  $w_t^*$  into (6) gives

$$L^* = -\frac{1}{2} \sum_{t=1}^{T} \frac{\left(\sum_{n \in I_t} g_n\right)^2}{\sum_{n \in I_t} h_n + \lambda} + \gamma T$$

# Split finding

- In optimized loss we have fixed optimal weight  $w_t^*$
- Optimized loss can also be used as impurity function in greedy one-step-ahead tree building.
- define *I* indexes of objects in the node, being split into left and right node
  - define  $I_L$ ,  $I_R$  indexes of objects inside left and right node
  - using  $L^*$  the split is found to maximize the gain:

$$\mathit{gain} = \mathit{L}^*_{\mathit{left}} + \mathit{L}^*_{\mathit{right}} - \mathit{L}^*_{\mathit{initial}} o \max_{\mathit{threshold}}$$

which is equal to

$$\frac{1}{2} \left[ \sum_{t=1}^{T} \frac{\left(\sum_{n \in I_{L}} g_{n}\right)^{2}}{\sum_{n \in I_{L}} h_{n} + \lambda} + \sum_{t=1}^{T} \frac{\left(\sum_{n \in I_{R}} g_{n}\right)^{2}}{\sum_{n \in I_{R}} h_{n} + \lambda} - \sum_{t=1}^{T} \frac{\left(\sum_{n \in I} g_{n}\right)^{2}}{\sum_{n \in I} h_{n} + \lambda} \right] - \gamma$$

# Additional extensions of xgBoost

- Shrinkage in xgBoost is the same as in usual boosting
- Subsampling is possible:
  - over objects
  - over features
- Approximate split finding possible
  - suppose N (number of objects) is large.
  - for continuous feature there may be up to N unique feature values.
  - instead of looking through all unique values, it is possible to look through fixed number of percentiles:
    - found once and for all nodes
    - or recalculated at each node

# Conclusion

- xgBoost is very successful gradient boosting open source implementation
- tree construction is not tied to specific criteria (entropy, gini) but is adapted to final user loss function
- optimized loss function has regularization, penalizing complex base learner trees.
- it is possible to optimize through a representative subset of feature values instead of all feature values by looping through percentiles.