Clustering - Victor Kitov

# Clustering

Victor Kitov

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- M-means
- 2 Hierarchical clustering
- Spectral clustering

#### K-means algorithm

- ullet Suppose we want to cluster our data into g clusters.
- Cluster i has a center  $\mu_i$ , i=1,2,...g.
- Consider the task of minimizing

$$\sum_{n=1}^{N} \rho(x_n, \mu_{z_n})^2 \to \min_{z_1, \dots z_N}$$
 (1)

where  $z_i \in \{1, 2, ...g\}$  is cluster assignment for  $x_i$ .

- Direct optimization requires full search and is impractical.
- K-means is a suboptimal algorithm for optimizing (1).

# K-means algorithm

```
Initialize \mu_j, j=1,2,...g.

repeat while stop condition not satisfied:

for i=1,2,...N:
  find cluster number of x_i:
  z_i = \arg\min_{j \in \{1,2,...g\}} ||x_i - \mu_j||

for j=1,2,...g:
  \mu_j = \frac{1}{\sum_{n=1}^N \mathbb{I}[z_n=j]} \sum_{n=1}^N \mathbb{I}[z_n=j]x_i
```

#### Possible stop conditions:

- cluster assignments  $z_1, ... z_N$  stop to change (typical)
- maximum number of iterations reached
- cluster means  $\{\mu_i, i = 1, 2, ...g\}$  stop changing significantly

# Dynamic K-means algorithm

```
Initialize \mu_i, i = 1, 2, ...g, z_i = 0, i = 1, 2, ...N
repeat while stop condition not satisfied:
     for i = 1, 2, ...N:
           find cluster number of x_i:
           z'_{i} = \arg\min_{i \in \{1,2,...g\}} ||x_{i} - \mu_{i}||
           if z_i'! = z_i:
                 recalculate cluster means \mu_{z_i} and \mu_{z'}:
                \mu_{z_i} = \frac{1}{\sum_{n=1}^{N} \mathbb{I}[z_n' = z_i]} \sum_{n=1}^{N} \mathbb{I}[z_n' = z_i] x_i
                \mu_{z_i'} = \frac{1}{\sum_{n=1}^{N} \mathbb{I}[z_n' = z_i']} \sum_{n=1}^{N} \mathbb{I}[z_n' = z_i'] x_i
                z_i = z'_i
```

Converges in less iterations, situation when no objects correspond to some cluster is impossible.

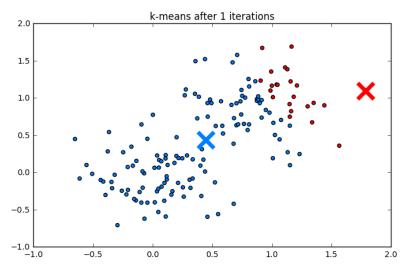
#### Initialization of cluster centers

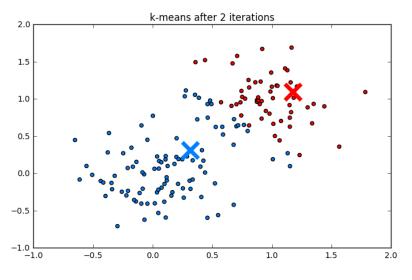
- We can initialize  $\{\mu_i, i = 1, 2, ...g\}$  with g randomly chosen measurements without replacement (typical)
- ② Alternatively we can initialize  $\{\mu_i, i = 1, 2, ...g\}$  with most distant set of points:

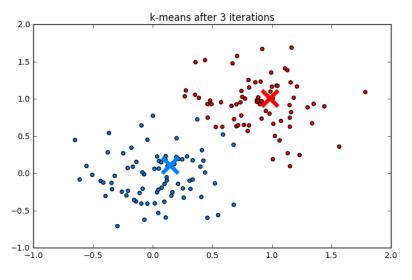
```
Estimate \mu = \frac{1}{N} \sum_{i=1}^{N} x_i. set \mu_1 = \operatorname{argmax}_{x \in x_1, \dots x_N} \rho(\mu, x) set \mu_2 = \operatorname{argmax}_{x \in \{x_1, \dots x_N\}} \{\rho(\mu_1, x)\} set \mu_3 = \operatorname{argmax}_{x \in \{x_1, \dots x_N\}} \{\rho(\mu_1, x) + \rho(\mu_2, x)\} .... set \mu_g = \operatorname{argmax}_{x \in \{x_1, \dots x_N\}} \{\sum_{i=1}^{g-1} \rho(\mu_i, x)\}
```

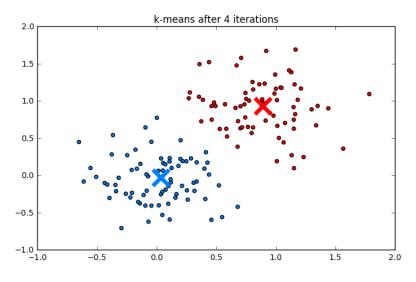
#### K-means properties

- Only local optimum is found
- Results depends on initialization
  - It is common to run algorithm multiple times with different initializations and then select the result minimizing criterion in (1).
- Complexity: O(NDgI), where g is the number of clusters and I is the number of iterations. Why?
  - If clusters exist, algorithm converges with few iterations and complexity is O(NDg)



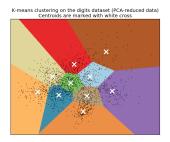






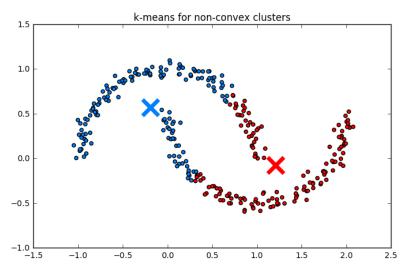
#### Gotchas

• K-means assumes that clusters are convex:

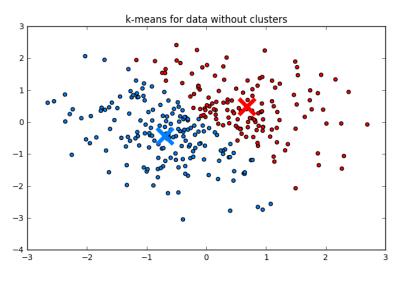


- It always finds clusters even if none actually exist
  - need to control cluster quality metrics

#### K-means for non-convex clusters



#### K-means for data without clusters



#### K-means and EM algorithm

```
Initialize \mu_j, j=1,2,...g. 

repeat while stop condition not satisfied: 

for i=1,2,...N: 

find cluster number of x_i: 

z_i = \arg\min_{j \in \{1,2,...g\}} ||x_i - \mu_j|| 

for j=1,2,...g: 

\mu_j = \frac{1}{\sum_{n=1}^N \mathbb{I}[z_n=j]} \sum_{n=1}^N \mathbb{I}[z_n=j]x_i
```

• K-means is EM-algorithm when:

# K-means and EM algorithm

```
Initialize \mu_j, j=1,2,...g. 

repeat while stop condition not satisfied: 

for i=1,2,...N: 

find cluster number of x_i: 

z_i = \arg\min_{j \in \{1,2,...g\}} ||x_i - \mu_j|| 

for j=1,2,...g: 

\mu_j = \frac{1}{\sum_{n=1}^N \mathbb{I}[z_n=j]} \sum_{n=1}^N \mathbb{I}[z_n=j]x_i
```

- K-means is EM-algorithm when:
  - applied to Gaussians
  - with equal priors
  - with unity covariance matrices
  - with hard clustering

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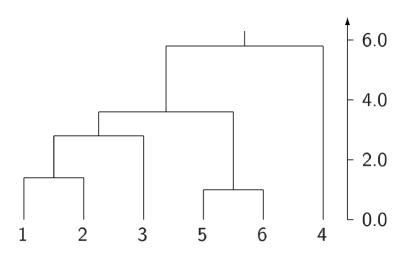
- 1 K-means
- 2 Hierarchical clustering
- Spectral clustering

# Hierarchical clustering

#### Hierarchical clustering may be:

- top-down
  - hierarchical K-means
- bottom-up
  - agglomerative clustering

# Agglomerative clustering



# Agglomerative clustering - distances

- Consider clusters  $A = \{x_{i_1}, x_{i_2}, ...\}$  and  $B = \{x_{j_1}, x_{j_2}, ...\}$ .
- We can define the following natural distances
  - nearest neighbour (or single link)

$$\rho(A,B) = \min_{\mathbf{a} \in A, b \in B} \rho(\mathbf{a},b)$$

furthest neighbour (or complete-link)

$$\rho(A,B) = \max_{a \in A, b \in B} \rho(a,b)$$

group average link

$$\rho(A, B) = \text{mean }_{a \in A, b \in B} \rho(a, b)$$

• centroid distance  $(\mu_U = \frac{1}{|U|} \sum_{x \in U} x)$ 

$$\rho(A,B) = \rho(\mu_A,\mu_B)$$

• median distance  $(m_U = median_{x \in U}\{x\})$ 

$$\rho(A,B) = \rho(m_a,m_b)$$

#### Agglomerative clustering - distance properties

- Suppose we modify distance  $\rho(x,x')$  with monotone transformation  $F: \rho'(x,x') = F(\rho(x,x'))$ . Which of the cluster distances will not be affected by this change?
- Lance-Williams recurrence formula:
  - $\rho(A \cup B, C)$  can be computed in O(1) time using  $\rho(A, C)$ ,  $\rho(B, C)$  and  $\rho(A, B)$

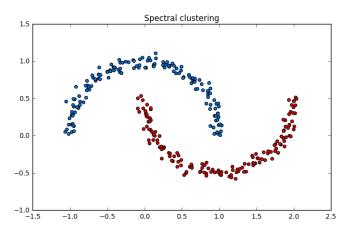
#### Agglomerative clustering - distance properties

- nearest neighbour may create stretched clusters
- furtherst neighbour creates very compact clusters.
- group average link, centroid and median distance give the compromise.
- however centroid and median distance may lead to non-monotonous joining distance sequences in agglomerative algorithm.
- in short group average link is preferred.

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# Spectral clustering - example



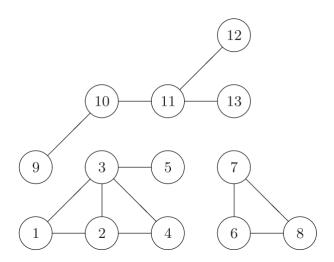
#### Description

- Spectral clustering reiles upon similarity matrix W between objects.
- Similarity matrix <-> weighted connection graph
- Examples:
  - nodes represent people, edge weights how much they communicate
  - ullet nodes represent web-pages, edge weights scalar products of TF-IDF

# Similarity matrix calculation

- $||x_i x_i|| < threshold$
- RBF
- based on nearest neighbours

# Graph with disjoint components



#### Graph Laplacian

- $W = W^T$ ,  $w_{ij} \ge 0$  the similarity between object i and object j.
- Define  $D = \operatorname{diag}\{d_1,...d_N\}$ , where  $d_i = \sum_{j=1}^N w_{ij}$ -weighted degree of node i.
- Define graph Laplacian

$$L = D - W$$

- Properties of graph Laplacian:
  - it is symmetric
  - It has eigenvector  $\mathbf{1} \in \mathbb{R}^N$  consisting of ones with eigenvalue 0. Why?
  - it is positive semi-definite:  $\forall f \in \mathbb{R}^N : f^T L f \geq 0$ .
  - L has eigenvalues  $\lambda_1 \geq \lambda_2 \geq ... \geq \lambda_N = 0$

#### Positive semi-definiteness of Laplacian

Consider arbitrary  $f \in \mathbb{R}^N$ :

$$f^{T}Lf = f^{T}Df - f^{T}Wf = \sum_{i} d_{i}f_{i}^{2} - \sum_{i,j,} f_{i}f_{j}w_{ij} = \frac{1}{2} \left( \sum_{i} d_{i}f_{i}^{2} - 2 \sum_{i,j} w_{ij}f_{i}f_{j} + \sum_{j} d_{j}f_{j}^{2} \right) = \frac{1}{2} \left( \sum_{i,j} w_{ij}f_{i}^{2} - 2 \sum_{i,j} w_{ij}f_{i}f_{j} + \sum_{j,i} w_{ji}f_{j}^{2} \right) = \frac{1}{2} \left( \sum_{i,j} w_{ij}f_{i}^{2} - 2 \sum_{i,j} w_{ij}f_{i}f_{j} + \sum_{i,j} w_{ij}f_{j}^{2} \right) = \frac{1}{2} \sum_{i,j} w_{ij}(f_{i} - f_{j})^{2} \ge 0$$

$$(2)$$

#### Eigenvectors of Laplacian

- Consider eigenvector f corresponding to eigenvalue  $\lambda = 0$ .
  - $f^T L f = \lambda f^T f = 0$
- Using (2) we have that

$$0 = f^{T} L f = \frac{1}{2} \sum_{i,j} w_{i,j} (f_i - f_j)^2$$
 (3)

- If objects i and j are connected on the graph, there exists a path with  $w_{uv} > 0$  along the path and from (3) it should be that  $f_i = f_j$ .
- So the set of eigenvectors of L is spanned by indicator vectors  $I_{A_1}, I_{A_2}, ... I_{A_K}$  where  $A_i$  is i-th isolated region on the graph.
- $\bullet$  Order of  $\lambda=0$  gives the number of isolated components.

#### Spectral clustering algorithm:

- Find order K of  $\lambda = 0$
- ② Find set of eigenvectors  $v_1, ... v_K$  corresponding to  $\lambda = 0$
- **3** Cluster rows of  $V = [v_1, ... v_K]$
- Each row corresponds to object with the same index. Found clustering is the final clustering of initial objects.

# Spectral clustering (unnormalized)

#### Unnormalized spectral clustering

Input: Similarity matrix  $S \in \mathbb{R}^{n \times n}$ , number k of clusters to construct.

- ullet Construct a similarity graph by one of the ways described in Section 2. Let W be its weighted adjacency matrix.
- ullet Compute the unnormalized Laplacian L.
- Compute the first k eigenvectors  $u_1, \ldots, u_k$  of L.
- Let  $U \in \mathbb{R}^{n \times k}$  be the matrix containing the vectors  $u_1, \dots, u_k$  as columns.
- $\bullet$  For  $i=1,\dots,n$  , let  $y_i\in\mathbb{R}^k$  be the vector corresponding to the i-th row of U .
- $\bullet$  Cluster the points  $(y_i)_{i=1,\dots,n}$  in  $\mathbb{R}^k$  with the k-means algorithm into clusters  $C_1,\dots,C_k$  .

Output: Clusters  $A_1,\ldots,A_k$  with  $A_i=\{j|\ y_j\in C_i\}$ .

#### Practical application

- $L' = D^{-1}L$  is considered instead of L ("Normalized" Laplacian)
  - to account for different connectivity levels of different nodes
- Most often singular values of L' are not exactly zero, but close to zero. So we select K smallest eigenvalues and corresponding K smallest eigenvectors.
- 2 Cluster rows of  $[v_1, ... v_K]$
- Found clustering is applied to objects with the same indexes.

# Normalized spectral clustering

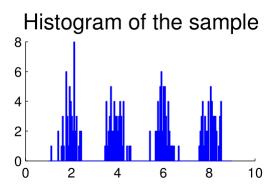
#### Normalized spectral clustering according to Shi and Malik (2000)

Input: Similarity matrix  $S \in \mathbb{R}^{n \times n}$ , number k of clusters to construct.

- ullet Construct a similarity graph by one of the ways described in Section 2. Let W be its weighted adjacency matrix.
- ullet Compute the unnormalized Laplacian L.
- ullet Compute the first k eigenvectors  $u_1,\ldots,u_k$  of the generalized eigenproblem  $Lu=\lambda Du$ .
- ullet Let  $U\in\mathbb{R}^{n imes k}$  be the matrix containing the vectors  $u_1,\ldots,u_k$  as columns.
- ullet For  $i=1,\ldots,n$ , let  $y_i\in\mathbb{R}^k$  be the vector corresponding to the i-th row of U .
- $\bullet$  Cluster the points  $(y_i)_{i=1,\dots,n}$  in  $\mathbb{R}^k$  with the k-means algorithm into clusters  $C_1,\dots,C_k$  .

Output: Clusters  $A_1, \ldots, A_k$  with  $A_i = \{j | y_j \in C_i\}$ .

#### Example



#### Example

